

Bump Mapping from a Normal Map to a Scene Pixel

Sebastian Enrique (senrique@cs.columbia.edu), Aner Ben-Artzi (aner@cs.columbia.edu)
Columbia University

Given the normal $\mathbf{n}$ (normalized) of a scene pixel and a normal map, where the (u, v) coordinates of the pixel on the map are known, we should find the rotation matrix $\mathbf{R}$ around an arbitrary axis $\mathbf{e}$ such that the rotated z axis of the normal map coincides with $\mathbf{n}$.

So, the axis of rotation must be the cross product between the z axis and the normal $\mathbf{n}$.

$$\mathbf{e} = \mathbf{z} \times \mathbf{n} = (0,0,1)^T \times (n_x, n_y, n_z)^T = (-n_y, n_x, 0)^T$$

Normalizing,

$$\bar{\mathbf{e}} = (\bar{e}_x, \bar{e}_y, \bar{e}_z)^T = \left(\frac{-n_y}{\sqrt{n_y^2 + n_x^2}}, \frac{n_x}{\sqrt{n_y^2 + n_x^2}}, 0 \right)^T$$

Now, we should find the rotation matrix such that,

$$R_{\bar{\mathbf{e}}}(\phi) \cdot \mathbf{z} = \mathbf{n}$$

$$R_{\bar{\mathbf{e}}}(\phi) \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} n_x \\ n_y \\ n_z \end{pmatrix}$$

Rotation matrix around an arbitrary $\mathbf{e}$ axis is defined as:

$$R_{\bar{\mathbf{e}}}(\phi) = \begin{pmatrix} \cos \phi + (1 - \cos \phi) \bar{e}_x^2 & (1 - \cos \phi) \bar{e}_x \bar{e}_y - \bar{e}_z \sin \phi & (1 - \cos \phi) \bar{e}_x \bar{e}_z + \bar{e}_y \sin \phi \\ (1 - \cos \phi) \bar{e}_x \bar{e}_y + \bar{e}_z \sin \phi & \cos \phi + (1 - \cos \phi) \bar{e}_y^2 & (1 - \cos \phi) \bar{e}_y \bar{e}_z - \bar{e}_x \sin \phi \\ (1 - \cos \phi) \bar{e}_x \bar{e}_z - \bar{e}_y \sin \phi & (1 - \cos \phi) \bar{e}_y \bar{e}_z + \bar{e}_x \sin \phi & \cos \phi + (1 - \cos \phi) \bar{e}_z^2 \end{pmatrix}$$

So,

$$R_{\bar{\mathbf{e}}}(\phi) \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} n_x \\ n_y \\ n_z \end{pmatrix} \Leftrightarrow R_{\bar{\mathbf{e}}}(\phi) = \begin{pmatrix} r_{00} & r_{01} & n_x \\ r_{10} & r_{11} & n_y \\ r_{20} & r_{21} & n_z \end{pmatrix}$$

Then,

$$\begin{aligned} \cos \phi + (1 - \cos \phi) \bar{e}_z^2 &= n_z \\ \cos \phi + \bar{e}_z^2 - \bar{e}_z^2 \cos \phi &= n_z \\ (1 - \bar{e}_z^2) \cos \phi &= n_z - \bar{e}_z^2 \end{aligned}$$

$$\cos \phi = \frac{n_z - \bar{e}_z^2}{1 - \bar{e}_z^2}$$

Replacing what we know from the normalized axis of rotation,

$$\cos \phi = n_z$$

Now we want to obtain the sinus,

$$\begin{aligned} (1 - \cos \phi) \bar{e}_y \bar{e}_z - \bar{e}_x \sin \phi &= n_y \\ (1 - n_z) \bar{e}_y \bar{e}_z - \bar{e}_x \sin \phi &= n_y \\ (1 - n_z) \bar{e}_y \bar{e}_z - n_y &= \bar{e}_x \sin \phi \\ \frac{-n_y}{\bar{e}_x} &= \sin \phi \end{aligned}$$

Analogous for n_x ,

$$\begin{aligned} (1 - \cos \phi) \bar{e}_x \bar{e}_z + \bar{e}_y \sin \phi &= n_x \\ (1 - n_z) \bar{e}_x \bar{e}_z + \bar{e}_y \sin \phi &= n_x \\ n_x - (1 - n_z) \bar{e}_x \bar{e}_z &= \bar{e}_y \sin \phi \\ \frac{n_x}{\bar{e}_y} &= \sin \phi \end{aligned}$$

So,

$$\sin \phi = \frac{-n_y}{\bar{e}_x} = \frac{n_x}{\bar{e}_y} = \sqrt{n_y^2 + n_x^2}$$

We can now write the final rotation matrix,

$$R_e(\phi) = \begin{pmatrix} n_z + (1 - n_z) \bar{e}_x^2 & (1 - n_z) \bar{e}_x \bar{e}_y & n_x \\ (1 - n_z) \bar{e}_x \bar{e}_y & n_z + (1 - n_z) \bar{e}_y^2 & n_y \\ -n_x & -n_y & n_z \end{pmatrix}$$

Given the normal **b** at coordinates (u,v) of the normal map, the new pixel normal **n'** is calculated as follows,

$$R_e(\phi) \cdot \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \begin{pmatrix} n'_x \\ n'_y \\ n'_z \end{pmatrix}$$

□